# PL-X957 CMOS | 10Gige | HDR | SONY IMX420 | GLOBAL SHUTTER

NENITAR COMPANY

The PL-X family of high performance machine vision cameras, with 10 Gigabit ethernet, offers speed, accuracy and reliability in a quick and easy set-up. The 10GBASE-T interface and packet resend capability provide high quality, reliable image transfer at cable lengths of up to 100m on CAT6A. Additional features include Power over Ethernet (PoE), Trigger over Ethernet (ToE) and IEEE1588 clock synchronization (PTP).

The Pixelink PL-X957 camera, featuring the Sony IMX420 4th generation Pregius CMOS sensor, is ideal for high dynamic range imaging applications requiring high resolution, fast frame rates, and high quality, low noise images.



A key feature of the IMX420 Sony sensor is a Dual ADC mode, where each pixel can be read out with two different gains. The PL-X957 combines the Dual ADC images into a single hybrid HDR image, directly on camera - thus removing the need for any host processing. Real time on camera HDR is an easy way for the user to gain 6-10dB of additional dynamic range on their image without taxing the CPU or requiring additional complex software algorithms.

# **KEY FEATURES**













MONO





**TYPICAL APPLICATIONS** 

Per Sec

Parts Inspection Strength / Stress Testing Scratch Inspection Automated Inspection Sports Analysis Research Broadcasting





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# **TECHNICAL SPECIFICATIONS**

## SENSOR

Sensor	Sony IMX420
Туре	CMOS Global Shutter
Resolution	7.1 MP (3208 x 2200)
Pixel Pitch	4.5μm x 4.5μm
Active Area	17.6 mm diagonal

## PERFORMANCE SPECIFICATIONS

FPN	<0.03% of signal
PRNU	<0.7% of signal
Dynamic Range	72 dB
Bit Depth	12 bit
Color Data Formats	Bayer 8, Bayer 12 Packed, Bayer 16, YUV422, RGB 24, BGR 24
Mono Data Formats	Mono 8, Mono 12 Packed & Mono 16

## FRAME RATES

Effective Resolution	Free Running
3208 x 2200	Up to 91 fps
Frame rate will vary based on he	ost system and configuration.

\* Above calculations based on fixed frame rate mode.

## INTERFACES

Board Level Trigger Connector	8-pin Molex 1.25 mm pitch
Enclosed Trigger Connector	Hirose M12 (12-pin)
Trigger	Software and hardware
Board Level Trigger Input	1 input, 3.3V (with internal pullup resistor)
Enclosed Trigger Input	1 optically isolated, 5-12V DC at 4-11 mA
Board Level GPO/Strobe	2 outputs, 3.3V
Enclosed GPO/Strobe	1 optically isolated, 5-12V DC at 4-11 mA, 2 outputs, 3.3V
Board Level GPI Input	1 input, 3.3v
Enclosed GPI Input	1 optically isolated, 5-12V DC at 4-11 mA
10GBase-T Connector	M12 X-coded (8-pin)

## MECHANICALS

Dimensions (mm)	125 x 57 x 57
Weight (g)	560
Mounting	C-Mount

## POWER REQUIREMENTS

Voltage Required

5V (from USB Type-C connector), 48V (802.3bt PoE)

## **PIN NAME & FUNCTION**

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1	3.3V power output
2	TRIGGER 3.3V HCMOS input
3	Ground
4	GPO1, 3.3V HCMOS output
5	GPO2, 3.3V HCMOS output
6	Clock, 3.3V (I2C access for OEMs)
7	Data, 3.3V (I2C access for OEMs)
8	GPI, 3.3V HCMOS input
	d connector: Molex (8-pin, 1.25mm pitch, vertical)
	receptacle: Molex 51021-0800; crimp terminals: Molex 50079-8100
ENC	LOSED GPIO INTERFACE PIN NAME & DESCRIPTION
1	5.0V output
2	TRIGGER + (optically isolated)

- 3 TRIGGER - (optically isolated)
- Data, 3.3V (I2C access for OEMs) 4
- 5 GPO1 + (optically isolated) 3.3V HCMOS output
- 6 GPO1 - (optically isolated)
- GPO1, 3.3V HCMOS output 7
- 8 GPO2, 3.3V HCMOS output
- 9 Ground
- 10 GPI+ (optically isolated)
- 11 GPI- (optically isolated)
- 12 Clock, 3.3V (I2C access for OEMs)

## **ENVIRONMENTAL & REGULATORY**

Compliance	FCC, CE & RoHS
Shock & Vibration	300 G to 20 G (10Hz-2KHz)
Operating Temperature	0°C to 50°C
Storage Temperature	-45°C to 85°C

## SOFTWARE

Pixelink Capture	Control & operate multi-camera
Pixelink SDK	Software Development Kit

COMPUTER & OPERATING SYSTEM	
Processor	Intel Core i5 or better ARMv7 (32-bit) or ARMv8 (64-bit) - ARMv8 recommended
Memory	8GB RAM or more - 16 GB multi-channel DDR4 recommended
Hard Drive Space	200MB - SSD recommended
BUS	PCIe 3.0 (or better) with a slot supporting x8 transfers
Operating System	Windows 7/8/10 - Windows 10 recommended Ubuntu 16.04/18.04/20.04

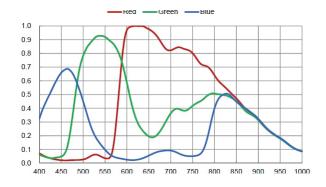


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## **RESPONSIVITY CURVES**

## **RESPONSIVITY CURVE- COLOR**



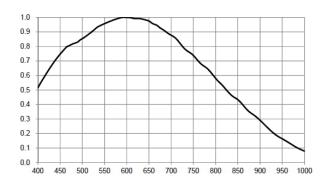
#### **PIXELINK CAPTURE**

Pixelink Capture is powerful multi-camera software application designed to configure "n" number of cameras and stream "n" number of cameras simultaneously in real-time high-quality video viewed in a multi-window environment. It offers options for complex image enhancements such as exposure control and filtering, in addition to multi-camera application testing and configuration.

Pixelink Capture features allow you to to measure supporting point, line, circle, rectangle, polyline and polygon measurements while determining pixel location. The user can review and adjust data before exporting the findings to an Excel spreadsheet for further analysis.

Pixelink Capture also has integrated lens control (zoom & focus) for Navitar motorized lenses and accurate autofocus options for Navitar motorized fine focus mechanisms.

#### **RESPONSIVITY CURVE- MONO**



#### **PIXELINK SDK**

Providing full control of all camera functions, the Pixelink Software Development Kit (SDK) is the software package of choice for developers and system integrators who are integrating Pixelink cameras into their applications. The Pixelink SDK provides access to the full Pixelink Application Programming Interface (API) and provides sample applications, wrappers for many 3rd party controls, such as LabVIEW, along with full documentation.

The Pixelink SDK is compatible with Microsoft Windows and popular Linux platforms. When using the Pixelink SDK, developers can integrate Pixelink cameras into their applications with ease.

## **AVAILABLE CONFIGURATIONS**

PL-X957CG-BL PL-X957CG-T PL-X957MG-BL PL-X957MG-T

COLOR SPACE C = Color M = Mono

NIR = Near Infrared

**INTERFACE** G= 10 GigE HOUSING BL = Board Level T = Trigger



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